

Unmanned Aerial Vehicles Technologies State-of-the-art

Where are we?

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Agenda

- Facts and Figures
- Technologies
 - Intro: Size does Matter and First Response
 - Dynamics, Control and Planning
 - State Estimation (Autonomy)
 - Swarm technology

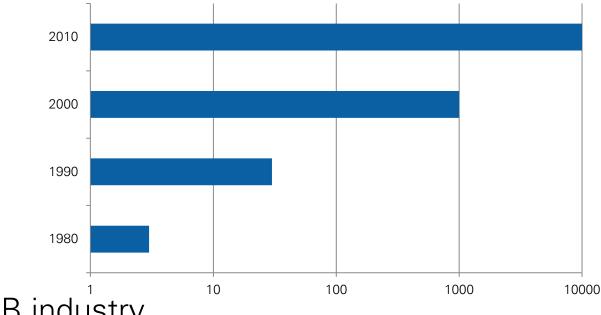


Facts and Figures



Unmanned Aerial Vehicles

Number of UAVs worldwide



> \$10B industry

- Military: Surveillance, force protection, warfare (> 75 countries)
- Civilian commercial: Transport, environment
- Civilian private: DIY Drones



More and more articles



How Drones Are Changing the Way We Do Business





image credit: senseFly



Creativity has rebooted business. Discover how through this ongoing series featuring unique products, services and technologies, as well as the personalities who have turned their dreams into our realities.

These days, if you're looking for drones, you don't have to look far. Also called unmanned aerial vehicles, these devices are being adapted from government to private use as tour guides and high-tech couriers. They're even finding their way onto film sets and archaeological digs. If Amazon has anything to do with it, we'll soon see them on our doorsteps.

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More and more startups growing here in Switzerland

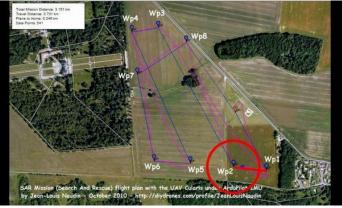






Search and Rescue







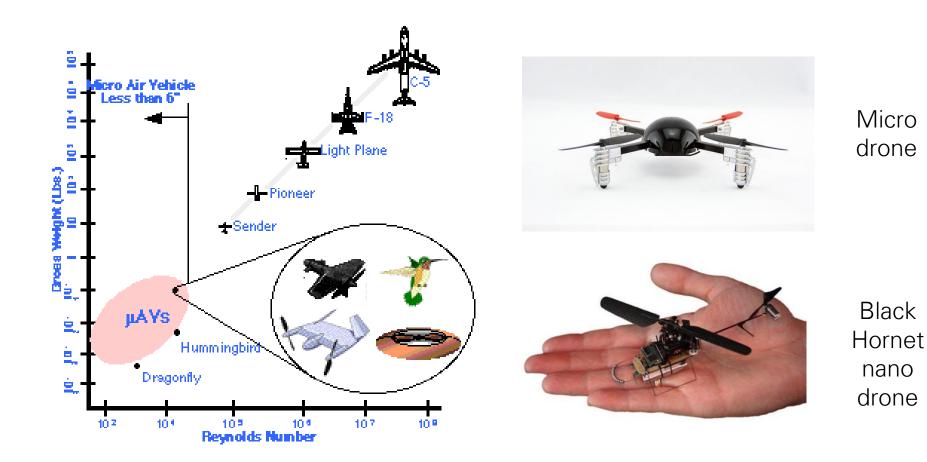








Comparison





Technologies



Technologies

Intro



Size does Matter



Linear Acceleration

~ 1/R

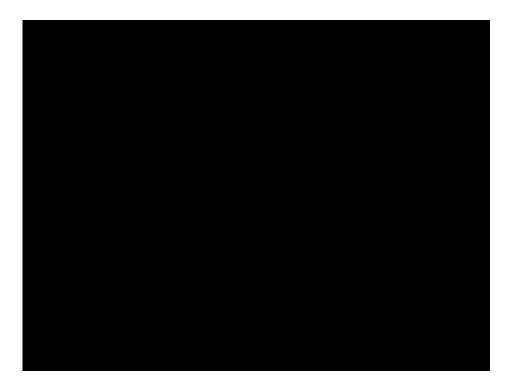
Angular Acceleration





First response

- Operate indoors and outdoors
- No GPS
- Small, maneuverable
- Agile, fast
- Operate in teams





Technologies



Technologies

Dynamics, Control and Planning



Agressive Maneuvring / Minimum Snap Trajectory



Mellinger and Kumar, ICRA 2011



Real-Time planning



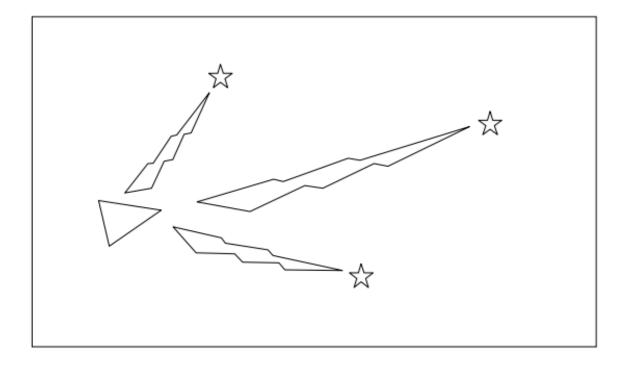
Mellinger and Kumar, ICRA 2011



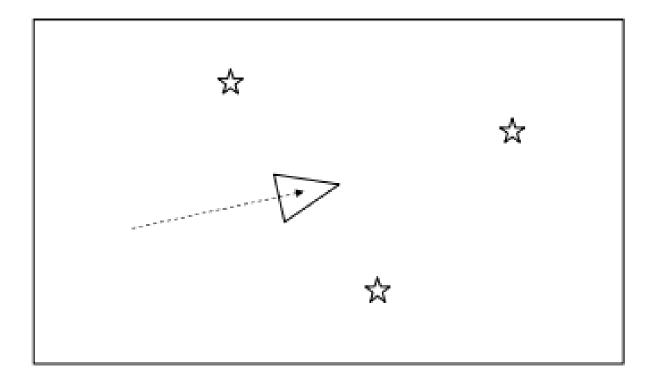
Technologies

State Estimation

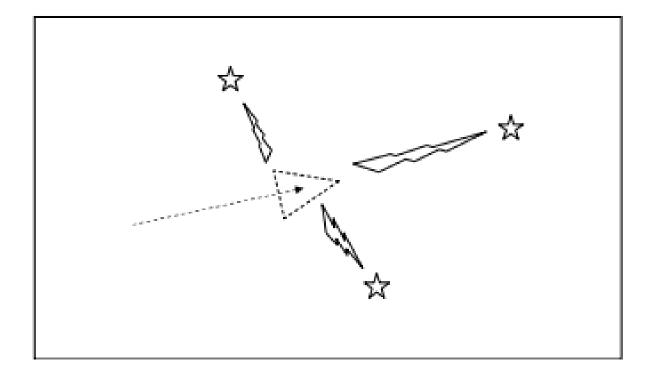




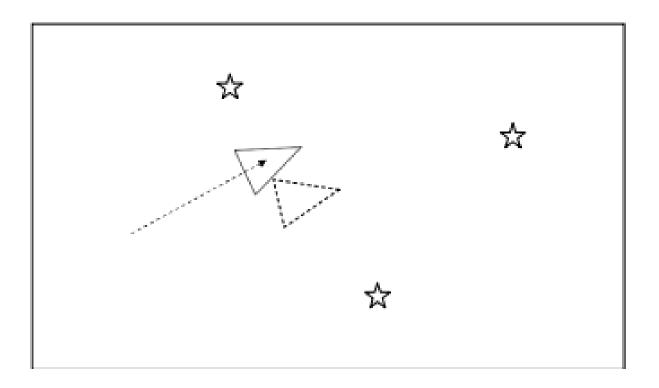




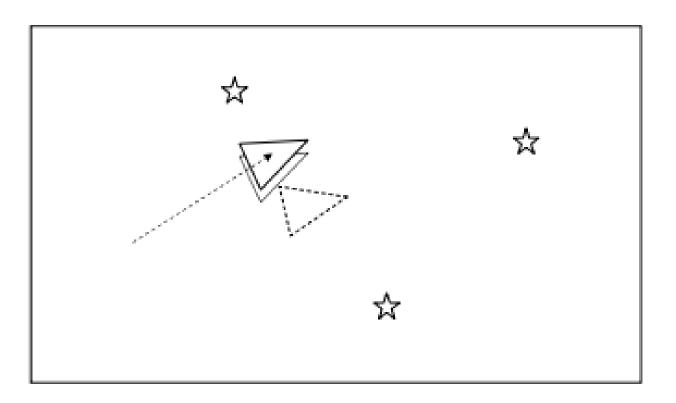














Onboard State Estimation



Korbinian Schmid and Haiko Hirschmüller



Technologies

Swarm Technology

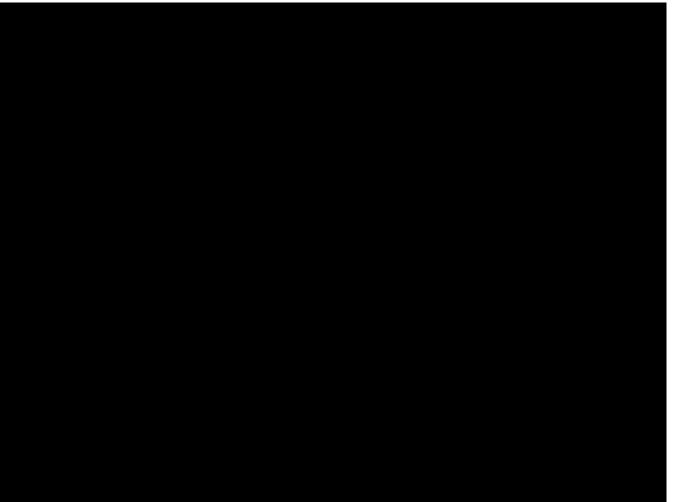


Swarm technology

- Act independently
- Require only local information
- Anonymous behavior



Control of Formation Shape and Group Motion



Kushleyev, Mellinger and Kumar 2012



Conclusion



Conclusion

- In the last two years flight controller consistency and reliability improved
- Cameras improved
- Batteries need to be improved



Amazing in Motion

Kmelrobotics / Lexus



Questions ?



